THE TOSHIBA MACHINE **EASY** ROBOT PHILOSOPHY

The Toshiba Machine SCARA is probably the world's easiest to use robot. Our entire philosophy is about making things straightforward for our customers. For us easy is a virtue. It means productivity, efficiency and professionalism. Easy is achieving what you want to achieve quickly and elegantly. It's the very essence of good engineering – making something that your competitors can make but making it better, more economically and quicker. We believe that our versatile, cost effective robots are the very embodiment of this thinking.

Easy to learn:

- Master programming with less than a day of training and find out how to input CAD data directly from files
- Discover our fast troubleshooting system with simple codes
- Estimate cycle times instantly, with no need for programming languages

Easy to integrate:

- The built in PLC enables complete system control from within the robot cell
- The simplicity of the robot teaching system means you can be up and running on a new programme in hours
- The easy plug and play integration with EZ vision saves time and money and makes your system massively more efficient

Easy to use:

- The largest range of arm lengths, payloads and options of any SCARA manufacturer
- High accuracy and repeatability regardless of payload
- High speed across the range, which means high productivity in your plant









Easy is productivity, efficiency, professionalism

TOSHIBA MACHINE

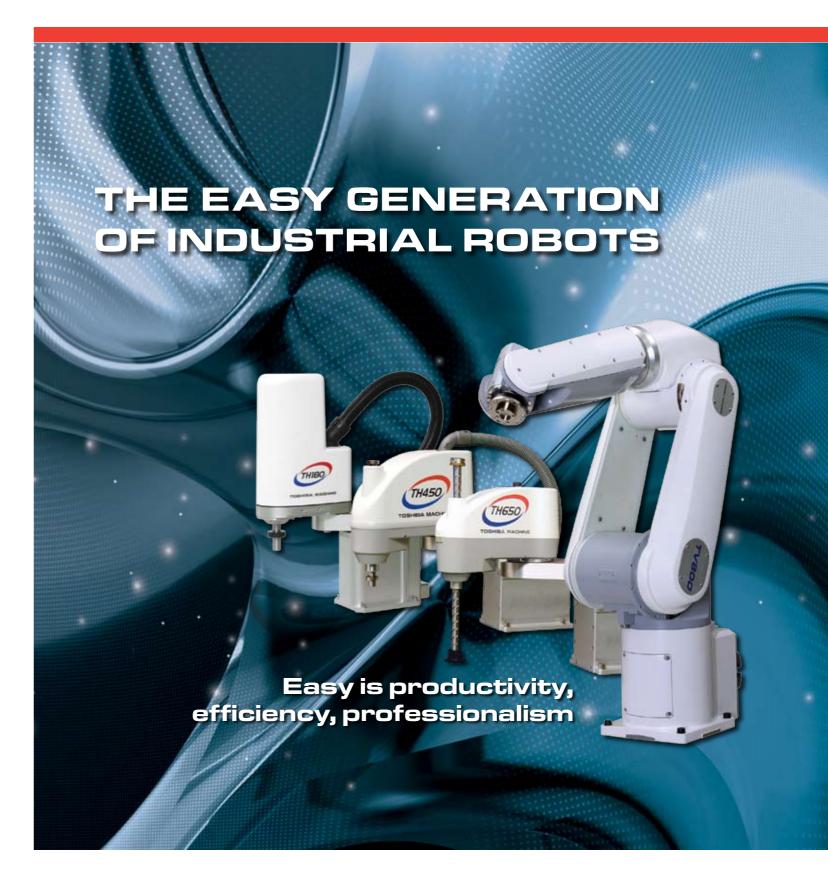
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TOSHIBA MACHINE

TOSHIBA MACHINE'S EASY-USE SCARA RANGE











COMPACT SCARA ROBOT

MODEL		TH180	TH250A	TH350A	
Arm length 1 st arm and 2 nd arm		180mm (70+110)	250mm (125+125)	350mm (225+125)	
	Axis 1	±120°	±115°	±115°	
Working	Axis 2	±140°	±140°	±145°	
envelope	Axis 3 (Z-axis)	120mm	120mm (150mm)	120mm (150mm)	
	Axis 4 (Z-axis rotation)	±360°	±360°	±360°	
	Axis 1	533°/sec	540°/sec	337.5°/sec	
Maximum	Axis 2	480°/sec	540°/sec	540°/sec	
speed	Axis 3 (Z-axis)	1013mm/sec	1120mm/sec 1120mm/sec		
	Axis 4 (Z-axis rotation)	1186mm/sec	1143°/sec	1143°/sec	
Composite		2.6m/s	3.53m/s	3.24m/s	
Standard cycle time		0.35s *1 (With 1kg payload)	0.41s *2 (With 1kg payload)	0.41s *2 (With 1kg payload)	
Maximum payload mass		2kg	3kg	3kg	
Allowable moment of inertia at end		0.01kg•m² *3	0.017kg•m² *3	0.017kg•m² *3	
Danastahilitu	X, Y, Z	±0.01mm	±0.01mm	±0.01mm	
Repeatability	Axis 4	±0.005°	±0.005°	±0.005°	
Input/output signals for hand		5 inputs / 4 outputs	5 inputs / 4 outputs	5 inputs / 4 outputs	
Air piping for hand		ф4×4 pcs	φ4×4 pcs		
Robot-controller cable length		3m (Option 5m)	3m (Option 5m)	3m (Option 5m)	
Mass	·	9kg	14kg	14kg	
Controller		TS1000	TS1000	TS1000	

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TH450A	TH550A	
450mm	550mm	
(200+250)	(300+250)	
±120°	±120°	
±145°	±145°	
150mm (300mm)	150mm (300mm)	
±360°	±360°	
600°/sec	375°/sec	
600°/sec	600°/sec	
2000mm/sec	2000mm/sec	
2000°/sec	2000°/sec	
7.33m/sec	6.21m/sec	
0.33s *2	0.33s *2	
(With 2kg payload)	(With 2kg payload)	
5kg	5kg	
0.05kg•m² *3	0.05kg•m² *3	
±0.015mm	±0.015mm	
±0.005°	±0.005°	
5 inputs / 4 outputs	5 inputs / 4 outputs	
ф4×4 pcs	φ4×4 pcs	
5m (Option max.25m)	5m (Option max.25m)	
27kg	29kg	
TS2000	TS2000	

ALLOWABLE MOMENT OF INERTIA

*3 The acceleration/deceleration rates may be limited depending on motion patterns, load mass and offset amount

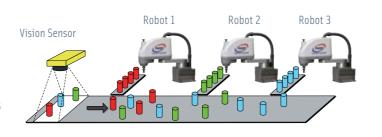
MOTION PATTERNS FOR STANDARD CYCLE TIME

- *1: 100mm for horizontal direction,
 25mm for vertical direction, round trip
- *2: 300mm for horizontal direction, 25mm for vertical direction, round trip

Share vision amongst multiple robots with conveyor synchronisation

Our 'one line = one camera' philosophy means you can:

- Cut costs by 'sharing' a single camera between all of the robots on a conveyor
- Sort large quantities and multiple types of workpieces and goods
- Take advantage of easy programming via dedicated commands
- Perfectly synchronized automation reduces damage to conveyed items



TOSHIBA MACHINE'S EASY-USE SCARA RANGE







HIGH SPEED, HIGH ACCURACY SCARA ROBOT

MODEL		TH650A	TH850A	TH1050A
Arm length 1st arm and 2nd arm		650mm (300+350)	850mm (350+500)	1050mm (550+500)
	Axis 1	±160°	±160°	±160°
Working envelope	Axis 2	±143°	±145°	±145°
	Axis 3 (Z-axis)	200mm (400mm)	200mm (400mm)	200mm (400mm)
	Axis 4 (Z-axis rotation)	±360°	±360°	±360°
	Axis 1	340°/sec	300°/sec	300°/sec
Maximum	Axis 2	600°/sec	420°/sec	420°/sec
speed	Axis 3 (Z-axis)	2050mm/sec	2050mm/sec	2050mm/sec
Axis 4 (Z-axis rotation)		1700°/sec	1200°/sec	1200°/sec
Composite		7.52m/sec	8.13m/sec	9.15m/sec
Standard cycle time		0.31s *2 (With 2kg payload)	0.39s *2 (With 2kg payload)	0.39s *2 (With 2kg payload)
Maximum payload mass		10kg	20kg	20kg
Allowable moment of inertia at end		0.1kg•m² *3	0.2kg•m² *3	0.2kg•m² *3
Dan and a billian	X, Y, Z	±0.01mm	±0.01mm	±0.01mm
Repeatability	Axis 4	±0.004°	±0.004°	±0.004°
Input/output signals for hand		5 inputs, 4 outputs	5 inputs, 4 outputs	5 inputs, 4 outputs
Air piping for hand		ф6×4 pcs	φ6×4 pcs φ6×4 pcs	
Robot-controller cable length		5m (Option max.25m)	5m (Option max.25m)	5m (Option max.25m)
Mass		51kg	76kg	80kg
Controller		TS2100	TS2100	TS2100

A simple solution to every challenge

OPTIONS

- Clean room class 10 (0.1 μ m 0.3 μ m)
 TH180 / TH250A / TH350A / TH450A
 TH550A / THP550 / TH650A / TH850A
 TH1050A
- Waterproof Design IP65

 THP550 / TH650A / TH850A / TH1050A

 (Limitation is imposed on acceleration/deceleration rates)
- Protective bellows for Z axis
 TH180 TH1050A / THP550
 Limited acceleration / deceleration
- Protective cover for Z axis
 TH650A TH1050A
- Ceiling Mount (T)
 TH350A TH1050A / THP550
- Optional cable lengths
 Between robot and controller:
 Maximum 10m (TH180 TH350A)
 Maximum 25m (TH450 TH1050A)
- **Teach pendant:** Maximum 15m
- Additional 5th Axis
 (Traverse, Wrist etc...) TH450 TH05

Straightforward control from the TS range

Dor anginer or W	ara control from c			
MODEL	TS1000	TS2000	TS2100	
No. of controlled axes	Standard 4 axes (Maximum 5 axes: TS2000/TS2100)			
Motion Modes	PTP (point-to-point), CP (Continuous Path; Linear, Circular), Sho	ort-Cut, Arch Motion	
Position Detection		Absolute encoders		
Storage capacity	Approx. Total: 64	00 points + 12800 steps 1 program: 2000 po	ints + 3000 steps	
No. of Registrable Programs	N	Maximum 256 (247 user files + 9 system files)	
Programming Language	SCOL (similar to BASIC)			
Teaching Unit	Teach pendant TP1000: Cable length 5 m / Programming support PC software TSPC also available			
External I/O Signals	16 inputs / 16 outputs 8/8 can be assigned to system signals	31+7 inputs / 22+10 outputs 7/10 can be assigned to system signals		
Hand Control Signals	5 inputs / 4 outputs			
External Operation Signal	Input: cycle operation mode, start, stop, program reset, etc. Output: Servo ON, operation ready, fault, etc.			
Serial Communication Ports	RS232C: 2 ports			
Power Supply and Capacity	Single phase AC190 V ~ 250 V, 50/60 Hz, 1.1 kVA	Single phase AC190 V ~ 250 V, 50/60 Hz, 2.3 kVA	Three phase AC190 V ~ 250 V, 50/60 Hz, 3.5 ~ 4.4 kVA	
Outer Dimensions and Mass	170W×290H×280D (mm)/10kg	290W×230H×280D (mm)/12kg	420W×230H×300D (mm)/16kg	
Other Functions	Interruption processing, robot motion ON signal, communication processing, arithmetic operation, torque limit, PLC, self-diagnosis, etc.			
PC Software for Programming Support (optional)	TSPC: Program editor, teaching, remote operation TCPRGOS: PLC sequence program creation (Supporting OS: Windows2000, WindowsXP)			
Options	Conveyor synchronization (not supported by TS1000), Additional I/O, I/O cable, position data latch function, smooth (constant speed) function, separated operation panel, network (Ethernet: Not supported by TS1000, CC-Link, DeviceNet, Profibus), CE-compliant			

COMPETING ON ALL FRONTS - NEW TOSHIBA MACHINE ROBOTS FOR EVERY PURPOSE



Six axis technology - completing the range

Toshiba Machine launched the TV800 cell robot in late 2008, introducing a six axis robot into its product portfolio for the first time. As a result, it is now one of the few robot suppliers across the globe to offer SCARA, six axis and Cartesian robot technology produced by a single manufacturer. The TV1000 was launched in 2009 and now provides a larger option for applications that require six-axis flexibility.

The TS3000 series controllers

Toshiba Machine's new range of TS3000 series controllers, comprising the TS3000 and TS3100, feature a built-in Ethernet port on both models, making conveyor and vision synchronisation simple. These controllers also

include the built-in TCmini PLC, which allows control of 1/0 equipment, regardless of operation and program. The net effect is greater efficiency and productivity, combined with savings in vision technology in a single easy to implement package.

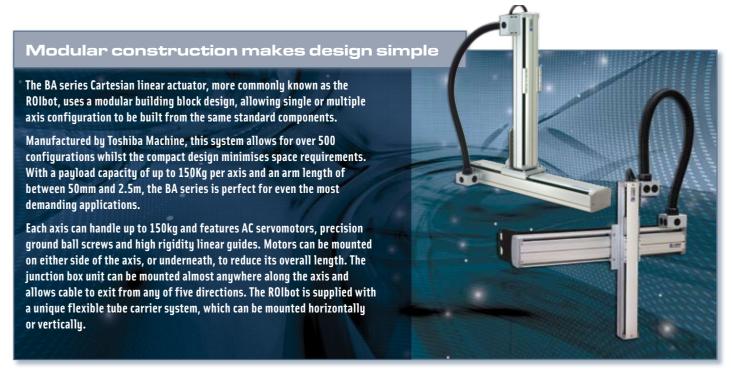


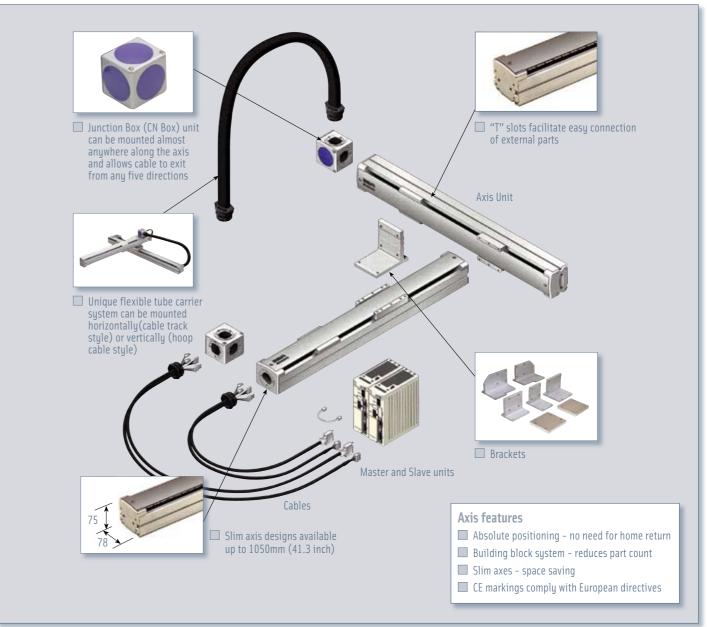
MODEL		THP550	
Туре		Horizontal multi-joint	
No. of controlled	axis	4	
Arm length		550mm (300+250mm)	
	Axis 1	±120°	
Working	Axis 2	±145°	
envelope	Axis 3 (Z-axis)	150mm (optional: 300mm)	
	Axis 4 (Z-axis rotation)	±360°	
	Axis 1	375°/s	
Maximum	Axis 2	600°/s	
speed	Axis 3 (Z-axis)	2000mm/s	
	Axis 4 (Z-axis rotation)	2000°/s	
Composite		6.21m/s	
Standard cycle time (with 1kg)		0.29s *1	
Maximum payloa	d mass	2kg	
Allowable momen	t of inertia	0.01kg.m ² *2	
Positioning	X-Y	±0.015mm *3	
repeatability	Axis 3 (Z-axis)	±0.01mm *3	
repeatability	Axis 4 (Z-axis rotation)	±0.02° *3	
Hand wiring		8 inputs/8 outputs	
Hand piping		4pcs (ø4)	
Position detection		Absolute	
Robot-controller	cable	5m (optional: max 25m)	
Mass		26kgs	

MODEL		TV800	TV1000		
Туре		Vertical Articulated Robot			
No. of controlled a	No. of controlled axis		6 axis		
	Total length	800mm	1000mm		
	1 st Arm	380mm	480mm		
Arm length	2 nd Arm	420mm	520mm		
	Reach	892mm	1090mm		
	Axis 1 (J1)	±170°			
	Axis 2 (J2)	-100~+150°			
Working	Axis 3 (J3)	-127~+167°			
envelope (deg)	Axis 4 (J4)	±190°			
	Axis 5 (J5)	±120°			
	Axis 6 (J6)	±360°			
	Axis 1 (J1)	237°/s			
	Axis 2 (J2)	240°/s			
Maximum	Axis 3 (J3)	288°/s			
speed(deg/sec)	Axis 4 (J4)	350.5°/s			
	Axis 5 (J5)	484°/s			
	Axis 6 (J6)	576°/s			
Composite		8.06m/sec	9.61m/sec		
Maximum payload mass		5kg			
Standard cycle time *2		0.4~0.5sec	0.6~0.7sec		
Allowable moment of Axis 4, 5		0.3kg/m ²			
inertia at end	Axis 6	0.05kg/m ²			
Positioning repeatability*3		±0.02mm(X-Y-Z) ±0.03mm(X-Y-Z)			
Position detecting system		Absolute system/AC servo motor			
Robot body	Robot body		48kg		

- *1: The acceleration/deceleration rates may be limited depending on motion patterns, load mass and offset amount.
- *2: Continous operation is not possible beyond the effective load ratio on the standard cycle time motion pattern. Horizontal 300mm, Vertical 25mm, round-trip
- *3: At constant temperature

CARTESIAN LINEAR ACTUATORS



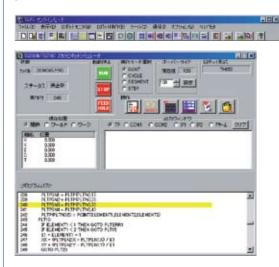


PROGRAMMING AND SIMULATION

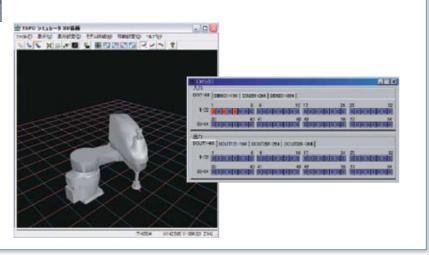
Software that makes system design and installation quick and easy

TSPC For robot programming

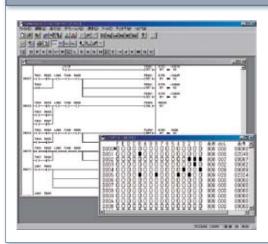
Toshiba Machine's TSPC software features a powerful simulation function which allows the user to create robot programmes after just basic training. This reduces lead times when integrating a robot and allows for pre-checking of new programmes, without stopping the production line.



- User friendly programming
- Extensive help section and syntax check
- Multi-function monitor and support
- Connection via Ethernet
- Active programme, position and alarm history displays



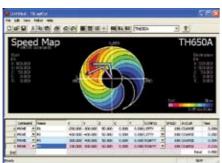
TCPRGOS For programming the built-in PLC

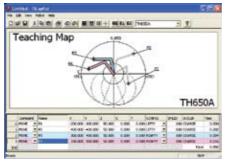


- Ladder style logic programming
- Online monitoring of ladder programme and I/O status helps reduce development and de-bugging time
- Functions include address map and comment displays and search

TS LayOut For cycle time and layout review

- Instant cycle time estimation: calculated by just pointing at a position with no need for programming language
- Guidance for high speed motion: coloured speed map indicates fast motion areas from a given start position, helping generate the most optimised system layout
- Conversion to robot programme: input positions can be converted to a robot programme with just one menu click

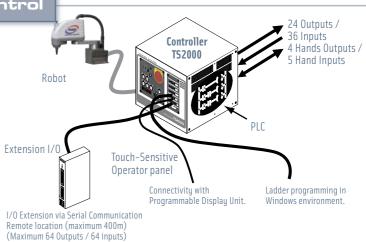


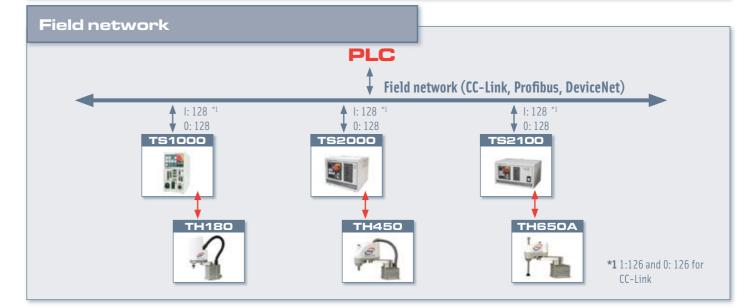


Built in PLC allows for total cell control

Toshiba Machine's TS series controllers all feature a built in TCmini PLC, which allows for control of I/O equipment, regardless of robot operation and programme. This allows for flexible system design and control of peripheral equipment, without the cost of an external PLC.

Input and output signals are handled via ladder style programming logic, which is independent from robot motion. Creation, monitoring and debugging of this programming is simple using Toshiba Machine's TCPRGOS-W support software. Connection to non Toshiba Machine programmable controllers and display units is a simple process and scan time is 5ms per 1-K word.





LEARN TO BE AN INDUSTRIAL ROBOT PROGRAMMER IN JUST 1 DAY

The TM Robotics SCARA Starter Pack is the ideal introduction to the world of easy to use industrial robot plug and play solutions.

THE **7** REASONS WHY THE STARTER PACK IS YOUR IDEAL ROBOT CHOICE:



- Small and fast your ideal first robot
- Plug and play works straight out of the box
- Portable ideal for training / demonstration
- Flexible transfer the robot from task to task
- True industrial robot not a stripped down version
- Easy to program no specialist knowledge required
- Pre-loaded programs and software no extra cost

Who should use the Starter Pack?

- Systems integrators
- Schools, colleges and universities
- Specialists looking for a robot offering
- End users of robots

What's included in the Starter Pack?

- Toshiba Machine TH180 micro SCARA robot
- TS1000 robot controller
- Teach pendant for easy control
- Portable robot and controller case and cell
- Preloaded example programs
- Pneumatic or electronic gripper options
- Training documentation
- Pre-drawn work surface to teach commands
- 700mm wide by 600mm high and 600mm deep